Time Frame: 7 weeks	Unit Title: Physical Computing	Course Name: Computer Science Grade 8	
Stage 1 - Desired Results			
Established Goals	Transfer		
NH CS Standards AP - Algorithms & Programming	Students will be able to independently use their learning to interact with the physical world.	build and program computing devices that react to and	
2-AP-10 - Use flowcharts and/or pseudocode to	Meaning		
address complex problems as algorithms.	UNDERSTANDINGS Students will understand that	ESSENTIAL QUESTIONS Students will keep considering	
 2-AP-11 - Create clearly named variables that represent different data types and perform operations on their values. 2-AP-12 - Design and iteratively develop programs that combine control structures, including 	Programming goes beyond the virtual world and into the physical world	How does software interact with hardware?	
	Computer programming languages are necessary to produce interaction between a user and a device. Physical computing devices receive information from	How can computers sense and respond to their environment?	
	users and the environment through inputs, and output reactions through connected hardware.	What kind of information can be communicated with hardware outputs?	
		How can simple hardware be used to develop innovative new products?	
nested loops and Acquisition		ition	

compound
conditionals.

- 2-AP-13 Decompose
 problems and
 subproblems into
 parts to facilitate the
 design,
 implementation, and
 review of programs.
- 2-AP-17 Systematically test
 and refine programs
 using a range of test
 cases.

Students will know...

- Input
- Output
- Conditionals
- Variables
- Loops
- Functions

Students will be skilled at...

- Programming microcontrollers to respond to input events with output
- Using conditionals to respond to sensor data
- Using variables to store data
- Using loops to solve problems by repeating commands in program
- Applying an iterator pattern to variables or properties in a loop
- Using functions to organize and reuse code
- Creating programs for a microcontroller which controls a physically constructed object

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